

# All watched over by machines of loving grace

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## Abstract

Modern operating systems are typically built around a trusted system component called the *kernel* which amongst other things is charged with enforcing system-wide security policies. Crucially, this component must be kept isolated from untrusted software at all times, which is facilitated by exploiting machine-oriented notions of separation: private memories, privilege levels, and similar.

Modern proof-assistants are typically built around a trusted system component called the *kernel* which is charged with enforcing system-wide soundness. Crucially, this component must be kept isolated from untrusted automation at all times, which is facilitated by exploiting programming-language notions of separation: module-private data structures, type-abstraction, and similar.

Whilst markedly different in purpose, in some essential ways operating system and proof-assistant kernels are tasked with the same job, namely enforcing system-wide invariants in the face of unbridled interaction with untrusted code. Yet the mechanisms through which the two types of kernel protect themselves are significantly different.

In this paper, we introduce *Supervisory*, the kernel of a programmable proof-checking system for Gordon’s HOL, organised in a manner more reminiscent of an operating system than a typical LCF-style proof-checker. *Supervisory*’s kernel executes at a relative level of privilege compared to untrusted automation, with trusted and untrusted system components communicating across a limited system call boundary. Kernel objects, managed on behalf of user-space by *Supervisory*, are referenced by handles and are passed back-and-forth by system calls. Unusually, *Supervisory* has no “metalanguage” in the LCF sense, as the language used to implement the kernel, and the language used to implement automation, need not be the same. *Any* programming language can be used to implement automation for *Supervisory*, providing the resulting binary respects the kernel calling convention and binary interface, with no risk to system soundness. Lastly, *Supervisory* allows arbitrary programming languages to be endowed with facilities for proof-checking. Indeed, the handles that *Supervisory* uses to denote kernel objects may be thought of as an extremely expressive form of *capability*—in the computer security sense of that word—and can potentially be used to enforce fine-grained correctness and security properties of programs at runtime.

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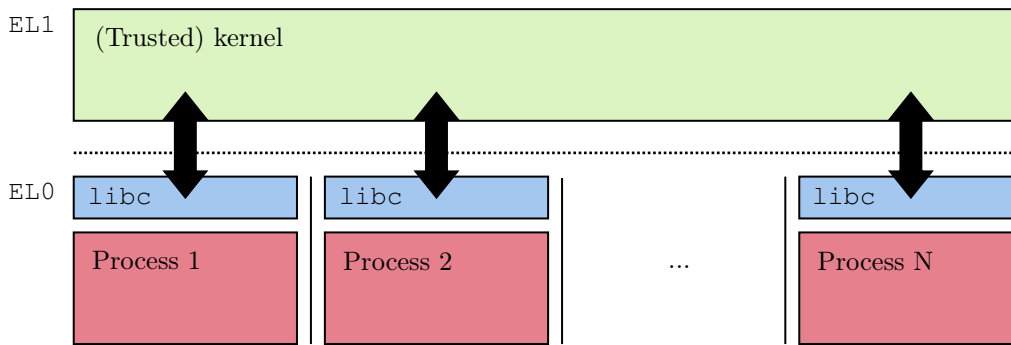
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## 1 Introduction

This paper studies the intersection of operating system design and implementations of the foundations of mathematics. Research into the confluence of these two topics is, admittedly, a rather moribund affair at the moment. Nevertheless, with this paper we hope to convince

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■ **Figure 1** A schematic of the typical system organization of a commodity operating system and its associated user-space. The kernel (in green) executes at a relative level of privilege, enforced by hardware, compared to processes executing in user-space (red)—we follow the Arm convention and show the kernel executing at EL1 and user-space at EL0. The two communicate across a system call boundary (dashed line) using system calls (black arrows). User-space programs are typically written making use of an abstraction library, such as `libc` (blue), to abstract over this kernel interface.

44 the reader that probing the intersection of these two areas is potentially very interesting  
 45 by introducing *Supervisory*, a programmable proof-checking system for Gordon’s HOL.  
 46 This system has a novel system design, with some interesting properties, and moreover some  
 47 interesting consequences. We first, however, begin with a scene-setting overview of common  
 48 principles in operating system design and implementation.

## 49 1.1 On operating systems

50 Most commodity operating systems—that is, Microsoft Windows and Unix-derivatives<sup>2</sup>—fit  
 51 a common pattern and are architected around a relatively self-contained, trusted component  
 52 typically called the system *kernel* [35].

53 The kernel is the sole component that can interface unfettered with all system resources,  
 54 including devices and other system hardware. Untrusted user-space applications make use of  
 55 kernel interfaces in order to make use of a device or any other system resource managed by  
 56 the kernel. As a result, the kernel is essentially a “pinch point” for gating access to system  
 57 resources. The kernel also introduces a process abstraction in user-space and is responsible  
 58 for ensuring the confidentiality and integrity of concurrently-executing processes, each of  
 59 which are mutually mistrusting. The kernel is therefore *the* key component responsible for  
 60 enforcing system-wide security policies, and essentially forms the “root of all trust” within  
 61 a computing system. It is therefore imperative that the kernel is itself isolated sufficiently  
 62 from user-space software at all times, lest this role be undermined by a malefactor.

63 The kernel self-isolates by co-operating with its host hardware. In support of this,  
 64 mainstream microprocessors have, over the years, accreted a variety of now-familiar security  
 65 features that an operating system kernel can use to defend itself from prying or interference.  
 66 These include *exception levels* or *privilege rings*, as they are variously called, depending on  
 67 the instruction set architecture, and which introduce a notion of *privilege* into the system.  
 68 Here, software executing at higher-privilege—in our case, an operating system kernel<sup>3</sup>—gains

<sup>2</sup> *Commodity* here is used to guard against pedantic quibbling over research operating system designs—like exokernels [9] and other oddities—which arguably do not fit this pattern.

<sup>3</sup> Note that *Cloud hosting* as a viable business proposition essentially rests on this trick being repeated

69 permission to program sensitive system registers, adjust hardware operating frequencies and  
70 voltages, and generally control how the system operates. Moreover, software executing at a  
71 higher-level of privilege can “peer in” and potentially modify the runtime state of software  
72 executing at a relatively lower-level of privilege, for example reading data from, or writing  
73 data to, a buffer within the memory space of an untrusted user-space process.

74 Modern microprocessors also provide a form of memory management built around page  
75 tables (see e.g. [3]). These data structures have a dual role: primarily, they are used for  
76 the virtualisation of system memory via address translation, granting user-space software  
77 the illusion that it owns the entire physical address space of the machine, presenting a  
78 *virtual* address space to user-space programs. This translation process induces a notion of  
79 ownership of pages of physical memory within the system, with a page of physical memory  
80 “owned” by a principal—either the operating system, a user-space process, or both—if it is  
81 *mapped in* to that principal’s address space. Moreover, page tables are also used for storing  
82 the metadata attributes of pages of memory, including read-write-execute permissions. By  
83 correctly initialising and managing these tables the kernel can keep its own code and data  
84 structures isolated—in a kernel-private memory area—that only it can access, safe from  
85 prying or interference by untrusted user-space. As a result, for systems software on modern  
86 computers, isolation is enforced by a mix of low-level machine mechanisms: separate address  
87 spaces, private memory regions, and machine-enforced privilege checks on executing software.

88 To make itself useful, the kernel exposes a limited interface, used by user-space to request  
89 intercession by the kernel on its behalf—for example by granting user-space access to some  
90 device, the filesystem, a socket, or some other system resource under kernel management.  
91 Dealing in generalities, to do this, the kernel exposes a suite of largely synchronous *system*  
92 *calls* which can be invoked by user-space programs with dedicated machine instructions  
93 provided by the microprocessor—see Figure 1 for a diagrammatic schematic, for example. On  
94 Arm platforms, with which the author is most familiar, these instructions induce a processor  
95 exception, forcing a *context switch* which flips the flow of control into the kernel’s system  
96 call handler, before eventually returning the flow of control back to the calling user-space  
97 program. From user-space’s point-of-view, system calls therefore have the appearance and  
98 effect of very CISC-like machine instructions, with the operating system kernel essentially  
99 presenting itself to user-space as *silicon by other means*, extending the user-space fragment  
100 of the instruction set architecture of the microprocessor with new macro instructions.

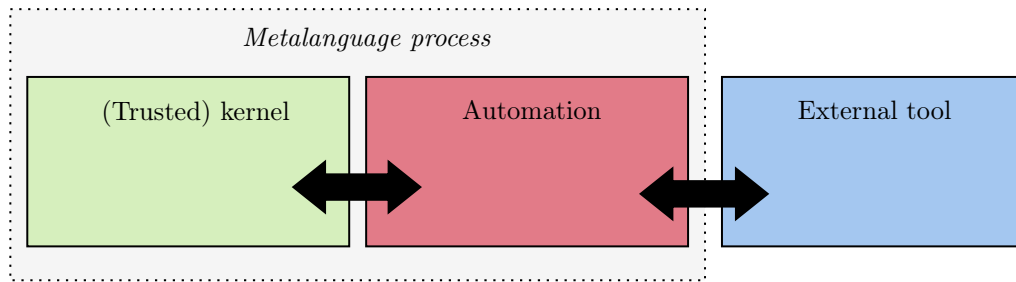
101 Note that for this two-way dance to work, user-space and the kernel must work together  
102 by adopting a series of joint conventions. These include a *calling convention* describing  
103 how arguments and results are passed back-and-forth across the system call interface, and  
104 a *binary interface* detailing how system calls are identified, how errors are reported back  
105 to user-space, and other miscellanea.<sup>4</sup> To help programmers adhere to these conventions,  
106 the operating system typically provides an abstraction layer to user-space, which on Unix  
107 variants typically takes the form of the system’s C library, `libc`. Generally, this is just a  
108 convenience, and user-space software may invoke system calls directly if wanted by invoking  
109 the correct machine instruction and adhering to the appropriate calling convention.<sup>5</sup>

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again, with a hypervisor sat in a position of privilege compared to an operating system kernel—executing out of an even higher exception level—and enforcing separation betwixt operating system instances.

<sup>4</sup> For more detail on the role of the system ABI, its other aspects, and its very real effects on the semantics of executing programs, see this [18] outrageously well-written yet criminally under-cited overview.

<sup>5</sup> This is the case on Linux, though does not hold universally on all Unix derivatives. For example Apple’s MacOS and some BSD Unix variants generally consider the programming interface of the system C library as the interface of the kernel, proper, in some cases preventing any user-space code other than



■ **Figure 2** A schematic of the system organisation of a typical LCF-style proof assistant. The trusted kernel (green) is linked against untrusted automation (red) existing within the same metalanguage process (dotted line) and communicate with each other using the kernel’s API (leftmost black arrow). External tools existing as separate processes (blue), must communicate with a shim layer written in the proof assistant’s metalanguage to access the kernel (rightmost black arrow).

110 However, crucially, it is *generally* not the case that the operating system kernel and  
 111 untrusted user-space applications must be written in the same programming language for  
 112 this all to work. Whilst most operating system kernels are written in C, or a C-language  
 113 derivative, user-space programs can be written in a variety of languages, and are also  
 114 commonly composed of multiple libraries, written in different programming languages, linked  
 115 together. Despite this, all are able to make use of system resources exposed by the kernel’s  
 116 system call interface by ensuring that they adhere to the calling convention and binary  
 117 interface expected by the kernel. In this respect, for commodity operating systems, the  
 118 C-language may have prominence as a favoured language of system implementation, but  
 119 by-and-large it is not *special* or given an unduly prominent status by the kernel itself.

## 120 1.2 On programmable proof-checkers

121 Most modern proof-assistants—for example, systems in the wider HOL family [27, 14, 33],  
 122 Coq [15], Matita [4], NuPRL [2], and similar—fit a common pattern and are architected  
 123 around a relatively self-contained, trusted component typically called the system *kernel*.

124 The system kernel is the sole component that can authenticate claims as legitimate  
 125 theorems of the implemented logic. Untrusted automation, residing outside of the kernel,  
 126 must “drive” the kernel to derive a theorem on its behalf. The kernel is therefore *the*  
 127 component responsible for ensuring system-wide soundness, and represents the “root of  
 128 all trust” within the system. It is therefore imperative that the kernel is able to isolate  
 129 itself sufficiently from untrusted automation at all times. This kernel-centric method of  
 130 system organisation is known as *the LCF approach* after Milner’s eponymous system [11].  
 131 See Figure 2 for a diagrammatic representation.

132 Most modern proof-assistants tend to be written in a *metalanguage* which serves as the  
 133 implementation language for both the kernel and the majority of the untrusted automation  
 134 that modern proof-assistants provide to users. This metalanguage is typically a strongly-typed  
 135 functional programming language, for example an ML derivative such as OCaml or SML [22],  
 136 and which offers strong modularity and abstraction features. The kernel exploits these  
 137 programming language features to hide its own data structures from untrusted automation  
 138 and expose a carefully limited API for proof-construction and manipulation. Notably, in an

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the system’s `libc` library from invoking system calls directly, as a security mechanism.

139 LCF-style system, the *only* mechanism automation has for constructing an authenticated  
140 theorem is by using this API, with the inference rules of the logic exposed as a suite of *smart*  
141 *constructors* manipulating an abstract type of theorems. The kernel is therefore a “pinch  
142 point” for any proof-construction activity within the system.

143 Untrusted automation and the system kernel are linked together, and reside side-by-side  
144 in the same process when the proof-assistant is executed. As a result, system soundness  
145 ultimately rests on the soundness of the implementation metalanguage’s type-system—  
146 specifically its ability to correctly isolate module-private data structures and enforce type  
147 abstraction. Moreover, for systems that use ephemeral proof construction, and lack an  
148 explicit notion of serialised proof-representation such as a *proof-term* or similar, the system  
149 metalanguage is unique amongst all programming languages in that it is the *only* language  
150 capable of interfacing directly with the kernel which is, after all, “just” a module written  
151 written in that language like any other. Whilst an external tool, or automation written  
152 in another programming language, *can* interface with the kernel, it must do so indirectly,  
153 making use of a shim layer written in the system metalanguage.

### 154 1.3 Introducing the Supervisory system

155 As the text above intimates, the role of the kernel in both an operating system and in a proof-  
156 assistant is—at least in an abstract sense—the same: both components must enforce system-  
157 wide invariants in the face of unbridled interaction with untrusted code; both components also  
158 act as the “root of all trust” for their respective systems; both components act as “pinch points”  
159 that untrusted code cannot help interact with if it wishes to engage in some kernel-gated  
160 activity. Consequently, both types of kernel need to correctly isolate their data structures and  
161 runtime state from interference by untrusted code. However, the two mechanisms through  
162 which this self-isolation is enforced are different: for operating system kernels<sup>6</sup> self-isolation  
163 is enforced using machine-oriented mechanisms; for LCF-style proof-assistants, self-isolation  
164 is enforced using programming language-oriented mechanisms.

165 In this paper we introduce *Supervisory*, the kernel of a novel programmable proof-  
166 assistant for Gordon’s HOL.<sup>7</sup> *Supervisory*’s design has more in common with a typical  
167 operating system than comparable implementations of HOL. Specifically, the *Supervisory*  
168 kernel executes at a relative level of privilege compared to untrusted automation, which can  
169 be thought of as executing as a process in something akin to *Supervisory*’s version of  
170 “user-space”. The trusted kernel, and untrusted user-space, communicate across a system call  
171 boundary which is carefully designed in order to maintain system soundness.

172 One consequence of this design is that the *Supervisory* kernel immediately takes  
173 on a different character to an LCF kernel. All of the paraphernalia of a typical HOL  
174 implementation—type-formers, types, constants, terms, and theorems—are managed as  
175 *kernel objects* kept safely under the management of the kernel itself, in kernel-private memory  
176 areas. These kernel objects are never exposed *directly* to user-space, rather, they are  
177 manipulated by the *Supervisory* kernel on user-space’s behalf. Handles—which can be

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<sup>6</sup> Barring unikernels, or library operating systems, like Mirage [20, 21]. If we are really pushing this analogy note that unikernels are in some respects quite similar to LCF-style proof-assistants in this regard, having their kernel linked with untrusted “user-space” and separated using programming language features like modules, rather than privilege and memory isolation.

<sup>7</sup> Many of the ideas presented henceforth are logic-independent. Though we have chosen to use HOL the ideas presented herein can be applied to a wide variety of other logics and type theories with relatively straightforward changes.

178 thought of as pointers, indexing Supervisory’s private memories—are used by a user-space  
 179 process to identify kernel objects that the kernel should manipulate or query.

180 Notably, Supervisory is also not implemented in a typed functional programming  
 181 language, as is typical of most programmable proof-assistants, but is rather implemented in the  
 182 decidedly *unsafe* systems programming language, Rust [17]. Note that this decision introduces  
 183 no risk to system soundness, as Supervisory’s soundness ultimately rests on the continued  
 184 separation of kernel-private data from Supervisory’s analogue of user-space—using privilege  
 185 and private memories—and not on the type system of the implementation programming  
 186 language. Moreover, as user-space and kernel communicate across a defined system call  
 187 interface, untrusted user-space may also be written in *any* programming language capable of  
 188 producing code that is binary-compatible with the Supervisory kernel. Supervisory  
 189 therefore has no “metalanguage” in the LCF sense, but rather an implementation language,  
 190 with automation potentially written in multiple languages—maybe even a mix.

191 For ease of implementation and use Supervisory is implemented as a WebAssembly [12]  
 192 (Wasm henceforth) host. We extend a Wasm virtual machine with new system calls that  
 193 perform a context switch into Supervisory, which has its own memory isolated from  
 194 the memory of the executing user-space Wasm process running under its supervision, and  
 195 inaccessible to it. This separation is only one way: the kernel can “peer in” to the runtime  
 196 state of a running Wasm process and read from, or write to, its private memories. This  
 197 decision means we may experiment with the fundamental ideas behind Supervisory—  
 198 namely isolating the kernel using private memory areas, the split between kernel- and  
 199 user-space, a kernel system call interface—without becoming bogged down in extraneous  
 200 detail associated with the booting ceremony of a real machine, for example. Moreover, we  
 201 harness work on porting compiler and linker toolchains, allowing our user-space to be written  
 202 in any programming language with a toolchain capable of targeting Wasm. Supervisory’s  
 203 design will be fully described in Section 3.

204 Lastly, and more speculatively, Supervisory’s handles can be passed around a program,  
 205 between different programs executing concurrently or sequentially under Supervisory’s  
 206 management, or between the user-space program and the kernel. Whilst this property is not  
 207 unique to Supervisory—values of the abstract type of theorems may also be passed around  
 208 within any LCF-style system, for example—the objects which these handles denote need not  
 209 be necessary truths of pure mathematics, but can be contingent truths, themselves *functions*  
 210 of the runtime state of the program itself, or of the Supervisory kernel. Handles to these  
 211 theorems act as a form of *capability*, in the computer security sense of that word. This  
 212 property is unique to Supervisory, as it rests on Supervisory’s dual status as a proof-  
 213 assistant kernel, capable of generating and checking theorems, and an extension of a general  
 214 purpose virtual machine, capable of executing arbitrary programs. Here, Supervisory  
 215 exploits its status as a “pinch point” that user-space cannot help pass through in order to  
 216 have any sort of computational effect, to force user-space to pass a handle denoting a theorem  
 217 that *proves* that it is acting correctly, per some system-wide policy. Some ideas of how this  
 218 idea could develop are discussed later, in Section 4.

## 219 **2** Implemented logic

220 Supervisory implements a variant of Gordon’s HOL [10], a classical higher-order logic.  
 221 This can be intuitively understood as Church’s Simple Theory of Types [7] extended with  
 222 ML-style top-level polymorphism. We introduce the basics of this logic here, introducing  
 223 just enough material that the unfamiliar reader can follow the rest of the paper.

$$\begin{array}{c}
\frac{r : \tau}{\Gamma \vdash r = r} \quad \frac{\Gamma \vdash r = s}{\Gamma \vdash s = r} \quad \frac{\Gamma \vdash r = s \quad \Gamma' \vdash s = t}{\Gamma \cup \Gamma' \vdash r = t} \quad \frac{\phi \in \Gamma}{\Gamma \vdash \phi} \quad \frac{\Gamma \vdash \perp \quad \phi : \mathbf{bool}}{\Gamma \vdash \phi} \\
\frac{\Gamma \vdash r = s \quad \Gamma' \vdash t = u}{\Gamma \cup \Gamma' \vdash r t = s u} \quad \frac{\Gamma \vdash r = s \quad x_\tau \notin fv(\Gamma)}{\Gamma \vdash \lambda x_\tau. r = \lambda x_\tau. s} \quad \frac{}{\Gamma \vdash \top} \\
\frac{\Gamma \vdash \phi \quad \Gamma' \vdash \psi}{\Gamma \cup \Gamma' \vdash \phi \wedge \psi} \quad \frac{\Gamma \vdash \phi \wedge \psi}{\Gamma \vdash \phi} \quad \frac{\Gamma \vdash \phi \wedge \psi}{\Gamma \vdash \psi} \quad \frac{\Gamma \cup \{\phi\} \vdash \psi \quad \phi : \mathbf{bool}}{\Gamma \vdash \phi \longrightarrow \psi} \\
\frac{\Gamma \vdash \phi \longrightarrow \psi \quad \Gamma' \vdash \phi}{\Gamma \cup \Gamma' \vdash \psi} \quad \frac{\Gamma \vdash \phi \quad \psi : \mathbf{bool}}{\Gamma \vdash \phi \vee \psi} \quad \frac{\Gamma \vdash \psi \quad \phi : \mathbf{bool}}{\Gamma \vdash \phi \vee \psi} \quad \frac{\Gamma \vdash \phi = \psi \quad \Gamma' \vdash \phi}{\Gamma \cup \Gamma' \vdash \psi} \\
\frac{\Gamma \vdash \phi \vee \psi \quad \Gamma' \cup \{\phi\} \vdash \xi \quad \Gamma'' \cup \{\psi\} \vdash \xi}{\Gamma \cup \Gamma' \cup \Gamma'' \vdash \xi} \quad \frac{\Gamma \vdash \phi \longrightarrow \psi \quad \Gamma' \vdash \psi \longrightarrow \phi}{\Gamma \cup \Gamma' \vdash \phi = \psi} \\
\frac{\Gamma \vdash \exists x_\tau. \phi \quad \Gamma \cup \{\phi[x_\tau := y_\tau]\} \vdash \psi \quad y_\tau \notin fv(\psi) \cup fv(\Gamma) \cup \{x_\tau\}}{\Gamma \vdash \psi} \quad \frac{\Gamma \vdash \phi = \psi \quad \Gamma' \vdash \psi}{\Gamma \cup \Gamma' \vdash \phi} \\
\frac{\Gamma \cup \{\phi\} \vdash \perp \quad \phi : \mathbf{bool}}{\Gamma \vdash \neg \phi} \quad \frac{\Gamma \vdash \neg \phi \quad \Gamma' \vdash \phi}{\Gamma \cup \Gamma' \vdash \perp} \quad \frac{\Gamma \vdash \forall x_\tau. \phi \quad r : \tau}{\Gamma \vdash \phi[x_\tau := r]} \\
\frac{\Gamma \vdash \phi[x_\tau := r]}{\Gamma \vdash \exists x_\tau. \phi} \quad \frac{\Gamma \vdash \phi \quad x_\tau \notin fv(\Gamma)}{\Gamma \vdash \forall x_\tau. \phi} \quad \frac{s : \tau' \quad r : \tau}{\Gamma \vdash (\lambda x_\tau. s)r = s[x_\tau := r]} \quad \frac{\Gamma \vdash \exists x_\tau. \phi}{\Gamma \vdash \phi(\epsilon x_\tau. \phi)} \\
\frac{f : \tau \Rightarrow \tau' \quad x_\tau \notin fv(f)}{\Gamma \vdash \lambda x_\tau. (f x) = f} \quad \frac{\Gamma \vdash \phi \quad r : \tau}{\Gamma[x_\tau := r] \vdash \phi[x_\tau := r]} \quad \frac{\Gamma \vdash \phi}{\Gamma[\alpha := \tau] \vdash \phi[\alpha := \tau]}
\end{array}$$

■ **Figure 3** The Natural Deduction relation for Gordon’s HOL.

224 We fix a denumerable set of *type variables* and use  $\alpha, \beta, \gamma$ , and so on, to range arbitrarily  
225 over them. We work with *simple types* generated by the following recursive grammar:

$$226 \quad \tau, \tau', \tau'' ::= \alpha \mid f(\tau, \dots, \tau')$$

228 Here  $f$  is a *type-former* which has an associated *arity*—a natural number indicating the  
229 number of type arguments that it expects. If all type-formers within a type are applied to a  
230 number of types matching their arity we call the type *well-formed*—that is, arities introduce  
231 a trivial or degenerate form of *kinding* for types. We will only ever work with well-formed  
232 types in Supervisory. We write  $tv(\tau)$  for the *set of type-variables* appearing within a type,  
233 and write  $\tau[\alpha := \tau']$  for the *type substitution* replacing all occurrences of  $\alpha$  with  $\tau'$  in the  
234 type  $\tau$ . From the outset we assume two primitive type-formers built-in to the logic itself and  
235 necessary to bootstrap the rest of the material:  $\mathbf{bool}$ , the type-former of the Boolean type  
236 and also the type of propositions, with arity 0, and  $\neg \Rightarrow \neg$ , the type-former of the HOL  
237 function space, with arity 2. Note we will abuse syntax and also write  $\mathbf{bool}$  for the *type* of  
238 Booleans and propositions, and also write  $\tau \Rightarrow \tau'$  for the function space type.

239 For each well-formed type  $\tau$  we assume a countably infinite set of *variables* and *constant*  
240 *symbols*. We use  $x_\tau, y_\tau, z_\tau$ , and so on, to range over the variables associated with type  $\tau$ ,  
241 and similarly use  $C_\tau, D_\tau, E_\tau$ , and so on, to also range over the constants associated with



$$\frac{}{x_\tau : \tau} \quad \frac{}{C_\tau : \tau} \quad \frac{r : \tau \Rightarrow \tau' \quad s : \tau}{rs : \tau'} \quad \frac{r : \tau'}{\lambda x_\tau. r : \tau \Rightarrow \tau'}$$

■ **Figure 4** The typing relation on terms

242 type  $\tau$ . With these, we recursively define *terms* of the explicitly-typed  $\lambda$ -calculus, as follows:

$$243 \quad r, s, t ::= x_\tau \mid C_\tau \mid rs \mid \lambda x:\tau. r$$

244 Note that there is an “obvious” simple-typing relation on terms, which is presented in Figure 4.  
 245 We write  $r : \tau$  to assert that a derivation tree rooted at  $r : \tau$  and constructed according to  
 246 the rules in Figure 4 exists, or more intuitively, that  $r$  has type  $\tau$ . We call any term with a  
 247 type *well-typed*; we will only ever work with well-typed terms in Supervisory. Also, we  
 248 call a term with type `bool` a *formula* and use  $\phi, \psi, \xi$ , and so on, to suggestively range over  
 249 terms that should be understood as being formulae in the rest of the paper. We work with  
 250 terms identified up-to  $\alpha$ -equivalence, write  $fv(r)$  for the set of *free variables* of the term  $r$ ,  
 251 write  $r[x_\tau := t]$  for the usual *capture-avoiding substitution* on terms, and write  $r[\alpha := \tau]$  for  
 252 the recursive extension of the type substitution action to terms.

253 As with type-formers, from the outset we assume a collection of typed constants needed  
 254 to bootstrap the rest of the logic, summarised in the table below:

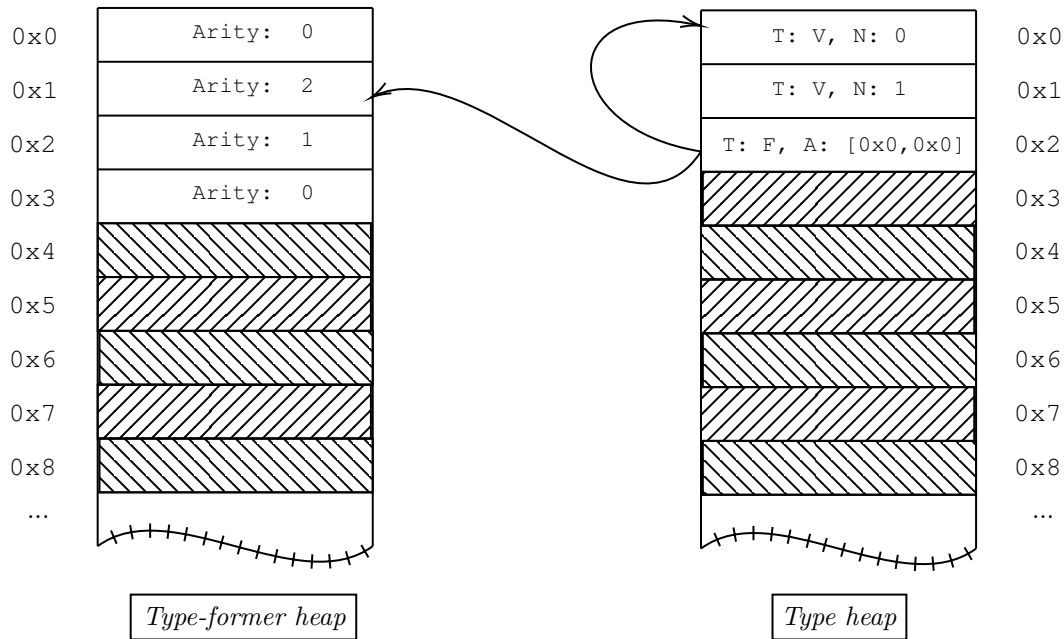
	=		$\alpha \Rightarrow \alpha \Rightarrow \text{bool}$
	$\top, \perp$		<code>bool</code>
	$\neg$		<code>bool</code> $\Rightarrow$ <code>bool</code>
255	$\wedge, \vee, \longrightarrow$	<i>with type</i>	<code>bool</code> $\Rightarrow$ <code>bool</code> $\Rightarrow$ <code>bool</code>
	$\forall, \exists$		$(\alpha \Rightarrow \text{bool}) \Rightarrow \text{bool}$
	$\epsilon$		$(\alpha \Rightarrow \text{bool}) \Rightarrow \alpha$

256 Most of the constants above are the familiar logical constants and connectives of first-order  
 257 logic, lifted into our higher-order setting, and are introduced without further explanation.  
 258 Only the  $\epsilon$  constant—Hilbert’s *description operator* [23], a form of choice—may be unfamiliar.  
 259 In HOL, this can be used to “select”, or “choose” an element of a type according to some  
 260 predicate, and is otherwise undefined if no such element exists. Note therefore that all  
 261 HOL types are inhabited by at least one element, with the term  $\epsilon x_\tau. \perp$  inhabiting every  
 262 type. We adopt conventional associativity, fixity, and precedence levels when rendering terms  
 263 using these constants, writing  $\phi \longrightarrow \psi$  instead of  $(\longrightarrow \phi)\psi$ , for example, and also suppress  
 264 explicit type substitutions required to make terms involving polymorphic types well-typed,  
 265 for example writing  $\forall x_\tau. \phi$  instead of  $\forall[\alpha := \tau](\lambda x_\tau. \phi)$ .

266 We call a finite set of formulae a *context*, ranged arbitrarily over by  $\Gamma, \Gamma', \Gamma''$ , and so on.  
 267 We write  $\Gamma[x_\tau := r]$  and  $\Gamma[\alpha := \tau]$  for the pointwise-lifting of the capture-avoiding substitution  
 268 and type substitution on terms to contexts, and write  $fv(\Gamma)$  for the set  $\bigcup\{fv(r) \mid r \in \Gamma\}$ . We  
 269 introduce a dyadic *Natural Deduction relation* betwixt contexts and formulae using the rules  
 270 in Figure 3, and write  $\Gamma \vdash \phi$  to assert that a derivation tree rooted at  $\Gamma \vdash \phi$  and constructed  
 271 according to the rules presented in this figure exists.

272 Note that our Natural Deduction relation can be simplified following the equational treat-  
 273 ment of the quantifiers and connectives discovered by Quine and Henkin, and implemented in  
 274 the HOL Light proof assistant [14], a point we touch on later in Section 5. We prefer a more  
 275 explicit treatment here, closer to a standard textbook presentation of Natural Deduction.





**Figure 5** Entries within the Supervisory kernel’s type heap referencing entries within the type-former heap. Cross-hatched heap cells are as-yet unallocated by the kernel. The cell allocated at address `0x2` in the type heap is tagged with the `F` tag, indicating it is a type-former applied to a list of argument types, and points-to the cell at address `0x1` in the type-former heap, with arity 2. Two copies of the type stored in the cell with address `0x0`, containing a type-variable with name 0, are used as the argument of the type-former to produce a complete, well-formed type. Adopting the convention that type-variable  $\alpha$  is at `0x0` in the type heap, and the function-space type-former  $\Rightarrow$  is at `0x1` in the type-former heap, then this represents an encoding of the type  $\alpha \Rightarrow \alpha$ .

276 **3 The Supervisory kernel state**

277 Supervisory’s kernel manages a series of *heaps*, or private memories, in addition to other  
 278 bits of book-keeping data. These heaps contain *kernel objects*, of various kinds: type-formers,  
 279 types, constants, terms, and theorems. These follow the progression of the different kinds of  
 280 HOL objects and their interdependencies, as introduced in Section 2.

281 **3.1 The type-former heap**

282 The most foundational of all of the heaps is the heap of type-formers, which is manipulated and  
 283 queried using a series of dedicated system calls. Each cell within the heap is either *unallocated*  
 284 or *allocated* and, in the latter case, contains a natural number *arity* for a type-former, encoded  
 285 as an unsigned 64-bit machine word. New type-formers are registered within the heap by  
 286 invoking a dedicated system call from user-space—`TypeFormer.Register`—which takes as  
 287 input the arity of the type-former and in response allocates a fresh cell, returning the address  
 288 of the cell back to user-space as the output of the system call. This address is the handle to  
 289 the new type-former kernel object, now under management by the Supervisory kernel,  
 290 and must be used by user-space to refer to this object henceforth. For example, a handle  
 291 can be passed to the system call `TypeFormer.IsRegistered` system call to test whether a  
 292 handle denotes a registered type-former. Alternatively, the `TypeFormer.Resolve` system  
 293 call can be used to *dereference* a handle, in order to obtain an arity, providing that it does

294 indeed denote a registered type-former, otherwise returning a defined error code.

295 Note that type-formers are essentially “named” by their handle: there may be many  
 296 type-formers with the same arity registered with the kernel, and the particular meaning of  
 297 any type-former is largely a convention of user-space, outside the purview of Supervisory.  
 298 Two primitive type-formers, pre-registered in the type-former heap on system boot, are  
 299 however exceptions to this rule and hold special significance for the kernel. These are the  
 300 `bool` type-former, registered at address `0x0` with arity 0, and the function-space type-former  
 301 `⇒`, registered at address `0x1`, with arity 2. The existence of these type-formers must be  
 302 understood by user-space, as they form part of the Supervisory system interface, similar to  
 303 how the distinguished file handles `stdout` and `stdin` are part of the POSIX system interface  
 304 and must be understood by user-space and kernel alike to support file I/O.

### 305 3.2 The type heap

306 Building atop the heap of type-formers is the heap of types, queried and manipulated using  
 307 another series of system calls, with the interface for working with types much more complex  
 308 than that for type-formers. As a result, it is only summarised here.

309 Recalling Section 2, types are either a type-variable or a *combination* of a type-former  
 310 applied to a list of types. All entries within the type heap are therefore tagged indicating  
 311 whether they are a type-variable or a combination. Type-variable entries contain one datum:  
 312 the *name* of the type-variable, an unsigned 64-bit machine word. Combination entries also  
 313 contain a pointer into the type-former heap, indicating which type-former is being applied,  
 314 and contain a list of pointers back into the type heap itself, identifying the type arguments of  
 315 the combination. Figure 5 shows a schematic diagram of dependencies between cells within  
 316 the two heaps, wherein we use **V** to tag type-variables and **F** to tag combinations.

317 Supervisory also boots with some entries in the type heap pre-registered, corresponding  
 318 to common or useful types used to bootstrap the rest of the logic. These include the Boolean  
 319 type, `bool`, common type variables— $\alpha$  and  $\beta$ , for example—as well as larger, more complex  
 320 types such as the type of the polymorphic equality,  $\alpha \Rightarrow \alpha \Rightarrow \text{bool}$ . The handles for all of  
 321 these pre-registered entities must likewise be understood by user-space.

322 Further derived types, built from primitive objects or otherwise, may be built using  
 323 `Type.Register.Variable` and `Type.Register.Combination` system calls for constructing  
 324 basic types. The first takes as input only a 64-bit machine word—the name of the variable—  
 325 and immediately registers a new type in the type heap, returning the newly-allocated handle.  
 326 On the other hand, `Type.Register.Combination` takes as input a handle pointing-to a  
 327 registered type-former in the type-former heap and a list of handles pointing back into the  
 328 type heap. The system call fails if any of these handles dangle, or denote an object of the  
 329 wrong kind, or if a list of type handles is presented with a length differing from the registered  
 330 arity of the type-former. Lists of handles are passed to system calls by passing a base pointer,  
 331 denoting the beginning of the list (or rather, array) with an explicit length. Substitutions,  
 332 for the `Type.Substitution` system call, which performs a type-substitution, are passed as  
 333 two lists: one for the domain of the substitution, another for the range.

334 It is sometimes convenient to test the structure of a type pointed-to by a handle. This  
 335 can be done using system calls like `Type.Test.Combination` which takes a handle and  
 336 returns a Boolean value indicating whether the corresponding type is a combination. A  
 337 family of “splitting” system calls—`Type.Split.Variable`, for example—can also be used to  
 338 deconstruct a type. This takes a handle and returns the name of the variable pointed-to by  
 339 the handle, if it is indeed a type-variable. Similar functions also exist for type combinations,  
 340 and allow user-space to “pattern match” on types.

341 A system call, `Type.Variables`, also exists for computing the type-variables appearing  
 342 within a term. Implementing this as a system call is a challenge as the number of variables  
 343 to be returned—and hence the size of buffer that user-space needs to set aside to hold  
 344 them, and which Supervisory will write into—is unpredictable. To resolve this, the kernel  
 345 exposes another system call, `Type.Size`, which computes the *size* of a type which bounds the  
 346 number of variables appearing within a type. By querying this, user-space can first allocate  
 347 sufficient memory within its own address space to hold the set of type-variables before calling  
 348 `Type.Variables` with a pointer to the base of the allocated buffer.

349 Obviously, the Supervisory kernel must be careful in its management of its heaps, and  
 350 this topic becomes pressing now we have introduced two heaps with dependencies between  
 351 them. In particular, Supervisory maintains a series of *kernel invariants* which hold  
 352 immediately out of boot and must be preserved by all system calls. One key invariant is the  
 353 idea that heaps only ever *grow* monotonically, and allocated entries are immutable. Once  
 354 an object is allocated into the heap it cannot be removed or modified in any way, lest we  
 355 introduce an unsoundness, for example by modifying the `bool` type, or the truth constant,  $\top$ ,  
 356 or something similarly catastrophic. Moreover, heaps should always remain *inductive*, in the  
 357 sense that their cells do not contain any dangling pointers that do not point-to allocated  
 358 cells in the same or other heaps. Essentially, this latter property forces the various objects  
 359 under Supervisory’s management to correctly follow the grammar of types and terms  
 360 introduced in Section 2, with larger objects being gradually “built up” out of smaller ones.

### 361 3.3 The constant and term heap

362 Building on the heap of types is the heap of constants, keeping track of registered term  
 363 constants. Again, this is pre-provisioned with a series of primitive constants, corresponding to  
 364 the logical constants and connectives, at boot-time. The system call interface for constants is  
 365 similar to that for type-formers, exposing just three system calls for registering new constants,  
 366 dereferencing handles, and testing whether a handle denotes a registered constant.

367 Another, further heap—the heap of terms—is also used to construct and manipulate  
 368 terms, with heap cells tagged with whether they represent a variable, constant, application, or  
 369 lambda-abstraction, in a similar style to the tagging used for cells in the type heap. System  
 370 calls for constructing, testing, and pattern matching on terms are provided, similar to those  
 371 previously discussed within the context of other heaps. Further, new special-purposes system  
 372 calls, for example `Term.Type.Infer` allow user-space to infer the type of a registered term,  
 373 if any, whilst `Term.Substitute` performs a capture-avoiding substitution on a term. Note  
 374 that handles for terms actually denote  $\alpha$ -equivalence classes of terms—at present, we use a  
 375 name-carrying syntax, but could implement this using De Bruijn indices or levels [8], leading  
 376 to a more efficient implementation.

### 377 3.4 The theorem heap

378 The final, and most important heap maintained by the Supervisory kernel is the heap of  
 379 theorems. Every other Supervisory heap exists to support this heap, and Supervisory  
 380 considers a theorem proved only if it appears in this heap. Cells within the theorem heap  
 381 contain a *sequent*, a tuple consisting of an (ordered) set of handles of formulae, representing  
 382 the assumptions of the theorem, combined with a single handle for the theorem’s conclusion.

383 A theorem kernel object can be deconstructed using the `Theorem.Split.Assumptions`  
 384 and `Theorem.Split.Conclusion` system calls, to obtain the list of assumption and conclusion  
 385 of the theorem object, respectively. However, the only way that a new entry in the heap

386 of theorems can be constructed is by using one of a series of system calls corresponding to  
 387 an inference rule of the logic’s Natural Deduction relation, presented in Section 2, or of the  
 388 definitional principles of HOL. Taking the *negation introduction* system call, for example:

$$389 \frac{\Gamma \cup \{\phi\} \vdash \perp \quad \phi : \text{bool}}{\Gamma \vdash \neg\phi}$$

390 We have a corresponding system call `Theorem.Register.Negation.Introduction` which  
 391 takes a handle pointing-to a sequent,  $\Gamma \cup \{\phi\} \vdash \perp$ , in the kernel’s theorem heap, and a handle  
 392 pointing-to a term,  $\phi$ , in the kernel’s term heap, and returns a handle pointing-to a theorem,  
 393  $\Gamma \vdash \neg\phi$ , also residing in the kernel’s theorem heap if all error checks pass for the inputs.

394 Like terms, theorem handles point-to  $\alpha$ -equivalence classes of theorem objects, wherein  
 395 two sequents are considered the same if their respective constituent handles point-to the same  
 396  $\alpha$ -equivalence classes of terms. Moreover, the Supervisory kernel also enforces *maximal*  
 397 *sharing* in all of its kernel heaps, and an attempt to register an object that has already been  
 398 registered, up-to  $\alpha$ -equivalence, does not allocate a new slot in the respective kernel heap, but  
 399 merely returns the existing handle to the object. These two decisions make some operations  
 400 within the Supervisory kernel easier to implement, at the expense of slowing down the  
 401 registering of new objects. For example, we know that objects are  $\alpha$ -equivalent when their  
 402 handles are identical. Moreover, in `Theorem.Register.Negation.Introduction` above, we  
 403 know that the formula  $\phi$  is not in the context  $\Gamma \cup \{\phi\}$  if the second input handle, mentioned  
 404 above, does not appear in the list of handles representing the assumptions of the sequent.  
 405 Note that this would not be the case if we did not enforce maximal sharing: *another* handle  
 406 pointing-to the term  $\phi$  may be present in the list of assumptions of the theorem, different  
 407 from the handle passed in from user-space, and this would force Supervisory to have to  
 408 perform a “deep scan” of its heaps in trying to work out whether the two handles supposedly  
 409 pointed-to the same HOL formula. As a result of this sharing, Supervisory’s heaps remain  
 410 inductive in the sense previously discussed, but recursively-defined objects represented within  
 411 them are not necessarily encoded as trees, but rather directed acyclic graphs.

412 Moreover, we previously mentioned that heaps must continue to grow monotonically at all  
 413 times, lest we inadvertently introduce an unsoundness into the system by allowing the HOL  
 414 `bool` type, or similar, to be redefined. However, note that this invariant *could* be weakened,  
 415 somewhat, by “working backwards” from the kernel’s theorem heap and removing objects  
 416 in other kernel heaps that are not referenced via a transitive points-to relation. Essentially  
 417 this would represent a form of *mark-and-sweep garbage collection* [31] wherein objects in  
 418 the kernel’s theorem heaps are root objects, with other objects deallocated if they are not  
 419 reachable from these roots. Care must be taken to ensure that the primitive kernel objects,  
 420 pre-provisioned into the heaps at system boot, can never be deallocated, even if currently  
 421 unreachable. Whilst possible, this garbage collection process is not at present implemented  
 422 in Supervisory, as sharing compresses the heaps with no pressing need to remove objects  
 423 from them. Moreover, within the context of garbage collection, user-space cannot be sure  
 424 that a handle generated by the kernel, and previously denoting a registered kernel object, is  
 425 stable and now does not dangle, complicating the Supervisory programming model.

### 426 3.5 Specifying kernel functions

427 Implementing and using the Supervisory kernel is an extended exercise in heap and pointer  
 428 manipulation, and until now the kernel’s system calls were explained in an intuitive, informal  
 429 sense. To specify the behaviour of some of our kernel system calls, we therefore reach for an  
 430 existing tool used to specify pointer-manipulating programs: Separation Logic [30, 16].

431 Working abstractly, we represent handles as elements of the set  $\mathbb{N}$  of natural numbers,  
 432 and use  $h, h', h''$ , and so on, to range over handles. For a fixed set  $A$ , we say that a  
 433 partial-function  $f : \mathbb{N} \rightarrow A$  is *finitely-supported* when the set  $\text{dom}(f) = \{x \mid f \text{ defined}\}$  is  
 434 finite. We call such a finitely-supported partial map into a set  $A$  an *A-heap*. We write  $0$  for  
 435 an empty *A-heap*, and for two *A-heaps*  $f$  and  $g$  we write  $f \# g$  to assert that their domains  
 436 are disjoint, so  $\text{dom}(f) \cap \text{dom}(g) = \{\}$ . This relation is symmetric and  $0 \# g$  always, for any  
 437  $g$ . Moreover, for two *A-heaps*  $f$  and  $g$  we can “glue them together”, using the function  $f \oplus g$ ,  
 438 to form a larger *A-heap*. This function is defined piecewise as:

$$\begin{aligned} 439 \quad & (f \oplus g) x = f x \text{ if } x \in \text{dom}(f) \\ 440 \quad & (f \oplus g) x = g x \text{ if } x \in \text{dom}(g) \\ 441 \quad & (f \oplus g) x \text{ is undefined otherwise} \end{aligned}$$

443 Note that  $f \oplus g$  is well-defined whenever  $f \# g$ . Finally, for  $a \in A$ , we write  $h \mapsto a$  for the  
 444 *singleton A-heap* mapping  $h$  to  $a$  and remaining undefined at all other points.

445 We define *types, constants, terms, and theorems* by the following non-recursive grammars,  
 446 where  $m$  ranges over arbitrary natural numbers:

$$\begin{aligned} 447 \quad & t, t', t'' ::= \text{TyVar } m \mid \text{TyFm } h (h_1, \dots, h_n) \\ 448 \quad & C, C', C'' ::= \text{TConst } h h' \\ 449 \quad & r, r', r'' ::= \text{Var } m h \mid \text{Const } h h' \mid \text{App } h h' \mid \text{Lam } m h h' \\ 450 \quad & s, s', s'' ::= \text{Seq } (h_1, \dots, h_n) h \end{aligned}$$

452 We call heaps over types a *type-heap*; similarly for constants, terms, and theorems. We also  
 453 call heaps over natural number arities a *type-former heap*.

454 Fix a set of kernel states  $K$ . We use  $k, k', k''$ , and so on, to range over kernel states,  
 455 each of which is a 5-tuple  $\langle F, Ty, C, Tm, Th \rangle$  consisting of a type-former heap, a type heap,  
 456 a constant heap, a term heap, and a theorem heap respectively. We extend our notion of  
 457 disjointness to kernel states, and write  $k \# k'$  to assert that all of the respective heaps in  
 458 kernel states  $k$  and  $k'$  are disjoint. We further abuse notation and write  $0$  for the *empty*  
 459 *kernel state* consisting of five empty heaps, and  $k \oplus k'$  for the “gluing” of two kernel states  
 460 together, wherein each of the respective heaps in  $k$  and  $k'$  are joined pointwise using  $\oplus$ . Note  
 461 that, again,  $k \oplus k'$  is well-defined whenever  $k \# k'$ .

462 We define *assertions* as sets of kernel states, use  $A, B, C$ , and so on, to range over them,  
 463 and write  $k \models A$  to assert that  $k \in A$ . We pay especial attention to some particular assertions  
 464 of note that will be useful in specifying some of our system calls:

$$\begin{aligned} 465 \quad & \bullet \equiv \{\langle 0, 0, 0, 0, 0 \rangle\} \\ 466 \quad & A \star B \equiv \{k'' \mid \exists k k'. k'' = k \oplus k' \text{ and } k \# k' \text{ and } k \models A \text{ and } k' \models B\} \\ 467 \quad & h \mapsto_{\text{Aty}} a \equiv \{\langle h \mapsto a, 0, 0, 0, 0 \rangle\} \\ 468 \quad & h \mapsto_{\text{Typ}} t \equiv \{\langle 0, h \mapsto t, 0, 0, 0 \rangle\} \end{aligned}$$

470 We further define the standard logical constants and connectives as abbreviations for setwise  
 471 operations, writing  $\perp$  for  $\{\}$ ,  $C \wedge D$  for  $C \cap D$ , and  $\exists x.C x$  for  $\bigcap_x . C x$ , for example.

472 Fix a set of *values*,  $V$ , consisting *at least* of handles and numeric error codes. System  
 473 calls  $e, f, g$ , and so on, are modelled as total functions from kernel states to kernel states  
 474 which also produce a value as a side-effect, that is  $e : K \rightarrow V \times K$ . Note that though a kernel  
 475 system call may fail—for example, if its inputs are in an unexpected form, or similar—it  
 476 should never *crash*, but rather return a specific error code back to the user-space program

477 and maintain the state of the kernel as it was before the system call was invoked. Crashes,  
 478 or *kernel panics*, are reserved for unrecoverable errors, for example the failure of an internal  
 479 invariant, or similar—the Supervisory equivalent of a “blue screen of death”.

480 With this in mind, we define a Separation Logic triple as a three-place relation between  
 481 an assertion, a system-call, and a function from values to assertions by:

$$482 \quad A \vdash e \dashv \lambda r. B \text{ iff for any } C \text{ if } k \vDash A \star C \text{ and } e k = \langle v, k' \rangle \text{ then } k' \vDash (\lambda r. B)v \star C$$

483 With this, we specify the behaviour of the `TypeFormer.Register` system call as follows:

$$484 \quad \bullet \vdash \text{TypeFormer.Register}(a) \dashv \lambda h. h \mapsto_{\text{Aty}} a$$

485  
 486 Note that this specification correctly captures the fact that the call can never fail: it will  
 487 always return a handle pointing-to a new cell in the type-former heap, containing the required  
 488 arity, with no other effects on the kernel heaps.

489 Specifying system calls which manipulate types, constants, terms, or theorems is more  
 490 complex as we must assume that any handles contained within these structures point-to  
 491 allocated cells in an appropriate kernel heap. To do this, we use of a family of *shape predicates*  
 492 relating encodings of objects within the kernel’s heaps to the recursively-defined structures  
 493 of Section 2. Assuming a bijection  $V$  between natural numbers and type-variables, and a  
 494 bijection  $F$  between handles and type-formers, we inductively define the relation `TYPE`  $h \tau$ :

$$495 \quad \frac{h \mapsto_{\text{Typ}} \text{TVar } m \quad (V \ m \ \alpha)}{\text{TYPE } h \ \alpha}$$

$$496 \quad \frac{h \mapsto_{\text{Typ}} \text{TyFm } h' \ (h_1, \dots, h_n) \star h' \mapsto_{\text{Aty}} n \star \text{TYPE } h_i \ \tau_i \quad (1 \leq i \leq n, F \ h' \ f)}{\text{TYPE } h \ f(\tau_1, \dots, \tau_n)}$$

498 We omit comparable shape predicates for constants, terms, and theorems, as the pattern  
 499 should be clear. Note that the basic allocation functions for types, upon success, generate  
 500 kernel states wherein the `TYPE` relation holds. For example, assuming a correspondence,  
 501  $V \ n \ \alpha$ , between the natural number  $n$  and type-variable  $\alpha$ :

$$502 \quad \bullet \vdash \text{Type.Register.Variable}(n) \dashv \lambda h. \text{TYPE } h \ \alpha$$

504 Similarly, we have:

$$505 \quad h \mapsto_{\text{Aty}} n \star \text{TYPE } h_1 \ \tau_1 \star \dots \star \text{TYPE } h_n \ \tau_n$$

$$506 \quad \vdash \text{Type.Register.TypeFormer}(h, h_1, \dots, h_n) \dashv$$

$$507 \quad \lambda r. h \mapsto_{\text{Aty}} n \star \text{TYPE } h_1 \ \tau_1 \star \dots \star \text{TYPE } h_n \ \tau_n \star \text{TYPE } r \ f(\tau_1, \dots, \tau_n)$$

509 Which also captures the fact that existing well-formed kernel heaps remain well-formed after  
 510 invocation of a system call, with shape predicate invariants formally capturing the kernel  
 511 invariants previously informally introduced.

## 512 3.6 Programming in user-space

513 The system call interface presents a very low-level, austere interface to user-space code. To  
 514 make programming Supervisory less tedious, a utility library, similar in function to `libc`,  
 515 is provided to user-space in order to raise the level of abstraction above the raw system  
 516 call interface. This is provided as `libsupervisory`, currently implemented only for  
 517 the Rust programming language, but could in theory be ported to the C-language, or any  
 518 other language that can be compiled to Wasm. Note that further layers, built on top of  
 519 `libsupervisory`, can provide pretty-printing and parsing routines for types and terms,  
 520 automation, proof-state management, and other functions typical of a proof-assistant.



## 4 Future work

We now take a more speculative turn, discussing future work. The ideas presented in this section are perhaps the most interesting consequence of Supervisory’s design, and we therefore dedicate a section solely to them.

### 4.1 Capabilities on steroids

As described, Supervisory is a proof-checking system implemented in an unusual way, but also a virtual machine, capable of executing arbitrarily complex programs compiled to the Wasm instruction set, from a variety of source programming languages.

However, at present, these Wasm programs are limited in the *effects* that they can make on the system—specifically, the only effect that they can actually make, other than heating the CPU, is to construct types, terms, and theorems, in Supervisory’s various heaps, using the series of system calls progressively introduced in Section 3. Programs executing under Supervisory are so-far incapable of opening files on the user’s machine, communicating over sockets, or querying the system time, because Supervisory does not provide any system calls to allow a program to perform any of those activities. However, it could.

Specifically, Supervisory could implement a system interface that provided all of the system calls needed by “real” programs wishing to make some effect on a user’s machine. By doing this, Supervisory is transformed into a general-purpose virtual machine, akin to the Java Virtual Machine, capable of executing arbitrary programs—calculators, simulations, file search utilities, and so on—albeit with a bizarre set of extra system calls dedicated to theorem proving. In short, by extending Supervisory with system calls for querying and manipulating the system state, Supervisory is *both* a proof-assistant and a general-purpose virtual machine—though these two facets of the system are kept separate.

These two families of system call need not be kept separated, however. Prior to allowing a user-space program to open or read a file, Supervisory could first demand that a (handle to a) theorem is supplied to it as an extra argument to the file-open system call, `fopen`, for example. Interestingly, because Supervisory executes at a relative level of privilege, and can “peer in” to the runtime state of a user-space program, the statement of this desired theorem can be a *function* of the runtime state of the user-space program itself, of the runtime state of the Supervisory kernel, and also of the various arguments and other details of the system call being invoked. This statement—which we will call the *challenge*—can be any arbitrary formula written in HOL, and can be generated dynamically by the kernel, perhaps in accordance with a *global policy* enforced by Supervisory. A failure to produce a handle to address a particular challenge causes the system call to fail, with a runtime failure.

For concreteness, suppose we fix HOL types `wstate`, `kstate`, and `cstate`, which you may imagine as being record types capturing details of the runtime state of the executing Wasm process, the runtime state of the Supervisory kernel, and the details of the system call being invoked. Supervisory can dynamically *reflect* the actual runtime states of the user-space program and kernel, and the invoked system call, into inhabitants of these HOL types. Then, supposing our prevailing security policy,  $p$ , is a HOL function of type `wstate`  $\Rightarrow$  `kstate`  $\Rightarrow$  `cstate`  $\Rightarrow$  `bool`, a challenge is obtained by dynamically applying  $p$  to the reflected records, described above. Two particularly special security policies exist:

$$\lambda w_{\text{wstate}}. \lambda k_{\text{kstate}}. \lambda c_{\text{cstate}}. \perp \quad \text{and} \quad \lambda w_{\text{wstate}}. \lambda k_{\text{kstate}}. \lambda c_{\text{cstate}}. \top$$

When applied to a reflected runtime state, these two policies generate the challenges  $\perp$  and  $\top$ , respectively. The first policy is therefore the *deny all* policy, which essentially prevents a



566 user-space program from invoking *any* system call, and making any effect on the system state,  
 567 whilst the second is the *allow all* policy which can always be trivially satisfied by passing  
 568 the handle to HOL’s truth introduction theorem.<sup>8</sup> Between these two extremal points are  
 569 a variety of other interesting policies, however. For example, if we assume that our `cstate`  
 570 record contains a field `cname` of type `cstate ⇒ string` capturing the name of the system call  
 571 being invoked, then we may selectively prevent particular system calls from being executed  
 572 by a program. The following policy prevents any invocation of the `fopen` and `fclose` system  
 573 calls from succeeding, for example:

574  $\lambda w_{\text{wstate}} \cdot \lambda k_{\text{kstate}} \cdot \lambda c_{\text{cstate}} \cdot \text{cname } c \notin \{\text{fopen}, \text{fclose}\}$

575 This policy is expressible using existing security mechanisms on mainstream operating systems:  
 576 modern Linux distributions use small eBPF programs to block programs from invoking  
 577 particular system calls at runtime, according to a security policy, for example. However,  
 578 the mechanism sketched above goes far beyond the expressivity of these existing systems as  
 579 *correctness* properties can also be captured by a policy, for example. Assume, for example,  
 580 that the `cstate` record also exposes a field `cargs` of type `cstate ⇒ nat ⇒ option list word 8`,  
 581 which returns the byte-representation of the  $n^{\text{th}}$  argument passed to the invoked system  
 582 call. With this, and assuming HOL functions `strbytes` and `intbytes` for converting string and  
 583 machine word datatypes into byte lists, respectively, we can then express

584  $\lambda w_{\text{wstate}} \cdot \lambda k_{\text{kstate}} \cdot \lambda c_{\text{cstate}} \cdot \text{cname } c = \text{fwrite} \longrightarrow$   
 585  $\text{cargs } c \ 0 = \text{Some } (\text{strbytes } \text{"foo.txt"}) \longrightarrow$   
 586  $\text{cargs } c \ 1 = \text{Some } (\text{intbytes } (\epsilon_{\text{word } 64} \cdot 3i^2 - 2i - 1 = 0))$   
 587

588 preventing any write to a file unless the 64-bit machine word being written is *some* zero of  
 589 a particular polynomial. In particular, the policy above demonstrates an important point:  
 590 Supervisory’s policies can use any aspect of HOL, quantifiers, choice, and all.

591 Until now, all examples have focussed on the `cstate` record which captures information  
 592 about the invoked system call. Other interesting policies can also be written in terms of the  
 593 runtime state of the Supervisory kernel itself. This idea becomes especially interesting if  
 594 we extend the kernel with new structures recording aspects of a program’s execution. By  
 595 extending Supervisory to keep a log of all system calls invoked thus far by a user-space  
 596 program—for example, exposing this log as a field `wlog` in the `wstate` record with type  
 597 `wstate ⇒ nat ⇒ option event`—we can capture *trace properties* of the executing program. For  
 598 instance, one may assert that system call invocations must be balanced in some way—exactly  
 599 one file may be opened at a time, and opening a second file first requires the program close  
 600 the other, for example—and also deeper properties, including adherence to a protocol.

601 One common security pattern deployed by software is gradual *jailing*, or shedding of  
 602 capabilities—for example, OpenBSD’s `pledge` system call allows a program to dynamically  
 603 shed the ability to further invoke particular classes of system call, gradually dropping  
 604 capabilities during a self-jailing phase. To offer a similar facility for Supervisory, we  
 605 need to allow a program to dynamically *strengthen* the prevailing policy being enforced by  
 606 Supervisory. Given the prevailing policy  $p$  we can allow the user-space program to self-jail  
 607 by switching to a new policy  $q$  if the program can *prove* to Supervisory that the new

---

<sup>8</sup> Note that, if we allow arbitrary axioms to be introduced into the Supervisory global theory, as many proof-assistants allow, then we need some form of *taint tracking* to ensure that challenges may only be answered by theorems deduced without axioms.

608 policy is more restrictive than the previous one, in the sense that:

$$609 \quad \forall w_{\text{wstate}}. \forall k_{\text{kstate}}. \forall c_{\text{cstate}}. q \ w \ k \ c \longrightarrow p \ w \ k \ c$$

610 If we view Supervisory's policies as identifying sets of possible system behaviours, then the  
 611 user-space program must prove to Supervisory's satisfaction that the set of permissible  
 612 behaviours that may occur from now on are a subset of the behaviours that Supervisory  
 613 was previously happy to accept. Note here that *quantification* is used in an essential way.

614 The material in this section has some similarity with an existing idea: *proof-carrying*  
 615 *code* [24]. In one model of proof-carrying code the operating system or virtual machine loader  
 616 is modified to check proof certificates bundled with binaries for adherence to some security  
 617 or correctness property, for example memory safety, before the binary is executed. Note,  
 618 however, that these certificates are constructed *up front*, in a separate step, and merely  
 619 checked by the operating system loader. In contrast, the ideas presented above are more akin  
 620 to *proof-generating code*, wherein the user-space program and Supervisory work together  
 621 to dynamically come to an understanding that the runtime behaviour of the program adheres  
 622 to a prevailing policy. In effect, HOL is used as a *lingua franca* used to communicate demands  
 623 by, and intent of, the Supervisory kernel and user-space program, respectively.

624 The ideas above also blur the lines between static and dynamic, or runtime, verification.  
 625 Supervisory can be used like any other proof assistant, to statically establish properties of  
 626 models of software or hardware systems, or reason about necessary truths within the rarefied  
 627 domain of pure mathematics. However, it may also be used to dynamically check the runtime  
 628 behaviour of programs executing under its supervision, interestingly also using theorem  
 629 proving. Moreover, Supervisory allows *any* program written in any programming language  
 630 to be endowed with support for theorem-proving, and reasoning about its own behaviour.  
 631 Indeed, a program executing on the Supervisory virtual machine *must* be prepared to  
 632 explain its adherence to the system security or correctness policy in order to have any hope  
 633 of performing a side-effect. With Supervisory, proof is no longer the exclusive domain of  
 634 dedicated programming languages like Agda [26] or Idris [6, 5], but can be extended to any  
 635 language merely by porting `libsupervisory`.

## 636 4.2 Hardware-accelerated proof-checking

637 As noted earlier, from the perspective of user-space software a system call presents as a suite  
 638 of particularly CISC-like machine instructions with a rather unorthodox method of invocation.  
 639 Indeed, the combination of the Supervisory system calls and the host Wasm instruction set  
 640 can be, itself, thought of as a new, derived instruction set extending Wasm, with strange new  
 641 domain-specific instructions for proof construction and management. Moreover, it should  
 642 be quite clear that there is nothing Wasm-specific about Supervisory, and indeed Wasm  
 643 was chosen merely as a relatively pain-free way of experimenting with the core ideas behind  
 644 Supervisory. Indeed, Supervisory could have been implemented as real, privileged  
 645 systems software for an existing instruction set in a relatively straightforward manner.

646 As a result, the Supervisory system call interface is already quite well-suited to  
 647 an implementation in hardware, perhaps as an extension of an existing instruction set  
 648 architecture like Arm AArch64 or RISC-V. The mechanism through which the Supervisory  
 649 kernel isolates itself, via private memories, is rather “hardware like”, and maps nicely onto  
 650 existing hardware features, and whilst the present Supervisory system call interface  
 651 makes extensive use of “pointer-like” handles to refer to kernel objects, on a real hardware  
 652 implementation these handles could *literally* be pointers into private memories, or similar.  
 653 Moreover, the system call interface itself is also further carefully designed to avoid arbitrarily

654 large recursive structures, difficult for an instruction set architecture to handle, from being  
 655 passed across the kernel system call boundary. We could therefore “push Supervisory  
 656 down one layer” again, into the underlying instruction set implemented by hardware. With  
 657 this, the ideas presented in Subsection 4.1 take on a new light, as the system hardware is now  
 658 capable of expressing, and enforcing, arbitrarily complex security and correctness properties.

## 659 **5** Conclusions

### 660 **5.1** Related work

661 The closest related work to Supervisory is *VeriML*, an ML-like language extended with  
 662 limited dependent-types ranging over HOL terms and theorems [34]. Essentially, VeriML  
 663 “internalises” a typical HOL kernel implementation within a higher-order programming  
 664 language, promoting the abstract type of theorems—typically *defined* within the system  
 665 metalanguage—into a native type of the language that can be queried and modified with  
 666 new, dedicated, domain-specific expressions for theorem construction and manipulation.

667 Compared to a typical HOL kernel, VeriML essentially “pushes the kernel down one layer”  
 668 in the hierarchy of abstractions, moving the kernel from a library within the language to  
 669 a first-class programming language feature. However, Supervisory “pushes” the kernel  
 670 even further, moving support for theorem proving out of the programming language and  
 671 into the underlying operating system—or, in our case, virtual machine. (And, as discussed  
 672 above, this “pushing” of the kernel down through the different layers of abstractions can  
 673 be taken to its logical conclusion, by pushing the kernel all the way into hardware.) Note,  
 674 however, that despite the general idea behind the two projects being essentially the same, the  
 675 two differ markedly in a myriad of design details which have some important consequences:  
 676 for example, automation in Supervisory is inherently programming-language agnostic,  
 677 whereas VeriML is inherently tied to one particular language—VeriML itself.

678 Interestingly, some of the ideas used in Supervisory can also be “pushed up one layer”  
 679 in the hierarchy of abstractions. Specifically, the Separation Logic specifications presented  
 680 in Subsection 3.5 can be re-interpreted as a series of *local axioms* describing the behaviour  
 681 of statements or expressions in a programming language for registering, manipulating and  
 682 querying type-formers, types, and other objects, in a series of heaps secreted from the user,  
 683 managed by the language’s runtime. Interestingly, the natural programming language that  
 684 one obtains from this exercise is imperative, in contrast to the functional VeriML. (To make  
 685 a more ergonomic programming language it would make sense for these expressions to be  
 686 modified so that they manipulate built-in recursive types of the programming language—  
 687 corresponding to HOL type-formers, types, constants, terms, and theorems—in a similar  
 688 fashion to VeriML, rather than make use of Supervisory’s handles and its incremental  
 689 construction of recursive structures.)

690 In Subsection 4.1 we observed that Supervisory’s handles can be reinterpreted as  
 691 *capabilities*, in the information security sense of that word. Note that capability machines are,  
 692 at the present time, having a minor renaissance, driven by the success of the CHERI capability  
 693 extensions for MIPS, Arm AArch64, and RISC-V [25]. Capabilities in hardware have a long  
 694 and storied history—dating at least to the Cambridge CAP machine developed in the 1970s—  
 695 and capability-based security has also previously been applied to programming languages and  
 696 software, including systems software like operating systems. Whilst contemporary operating  
 697 systems like seL4 [19] and other L4 derivatives have a security model built around capabilities,  
 698 perhaps the best well-known historical example of a capability-based operating system was  
 699 KeyKOS [29, 13] and its many derivatives, including EROS, the Extremely Reliable Operating

700 System [32]. However, despite this long history, the Supervisory conception of capabilities  
701 differs from other implementations as hardware-based capability systems like CHERI, are  
702 relatively inexpressive, merely extending traditional pointer types with information on valid  
703 memory regions within which they may point, and memory access permissions. This is  
704 because existing hardware-based capability systems are optimised to prevent spatial and  
705 temporal memory safety issues, inherent in the use of unsafe systems programming languages  
706 like the C-language, and derivatives, and must provide an easy “on ramp” allowing existing  
707 software to adopt them. Supervisory’s conception of capabilities differs, here, in being  
708 more expressive, allowing complex security and correctness properties to be expressed, but  
709 also much more intrusive, and much harder to make use of: software must be aware of the  
710 prevailing security or correctness policy in force at the time, when trying to open a file for  
711 example, in order to be able to correctly answer the “challenge”. Using a Supervisory  
712 capability to open a file may also require unbounded amounts of reasoning first, in order to  
713 address the “challenge” posed by Supervisory, which is not the case with other forms of  
714 capability, which act as passive tokens of authority.

715 Lastly, Supervisory, as an implementation of HOL, is closely related to several extant  
716 systems in the wider HOL family: Isabelle/HOL, HOL4, HOL Light, Candle [1], and so  
717 on. The kernels of all of these systems implement very similar logics, albeit with minor  
718 modification. However, unlike the aforementioned systems, Supervisory does not follow  
719 the typical LCF-style of system organisation, nor is it written in an ML-derivative.

## 720 5.2 On trust

721 The current Supervisory proof-checking kernel consists of approximately 6,600 lines of  
722 Rust code, compared to approximately 3,100 lines of Standard ML in recent distributions  
723 of the Isabelle framework. Whilst comparing linecounts between languages is an imperfect  
724 science, the Supervisory kernel is still clearly larger than one of the most complex extant  
725 LCF-style implementations. Largely, this is because Supervisory implements the HOL  
726 Natural Deduction relation in full, providing introduction and elimination rules for all logical  
727 constants, as observed in Section 2. Using a bare-bones implementation of HOL, based upon  
728 equality, and then deriving introduction and elimination rules for all other logical constants  
729 outside of the kernel, would be one way to shrink the kernel line count.

730 From the point-of-view of a Supervisory user-space program the kernel is not the  
731 only body of code that must be trusted. The implementation of `libsupervisory`—a  
732 mediation layer between kernel and user-space—must also be trusted in much the same way  
733 that `libc` must also be implicitly trusted by user-space on Unix-derivatives. A malicious  
734 `libsupervisory` could present as interfacing with the kernel whilst maintaining shadow  
735 copies of kernel state, never requesting that the kernel actually check a proof, for example! This  
736 threat is not unique to Supervisory—despite oft-repeated claims that the kernel represents  
737 the entire system TCB, users of all interactive theorem proving systems implicitly trust the  
738 system’s pretty-printer, for example, not to lie about what the system has proved [28], despite  
739 this code typically residing outside of the kernel—though the fact that there is a nuanced *threat*  
740 *model* here is perhaps more obvious, and pressing, as a consequence of Supervisory’s dual  
741 status as proof-checker and general-purpose virtual machine. Minimising the system kernel  
742 size potentially comes at the cost of bloating other code—for example, `libsupervisory`—  
743 that must also be trusted by users wishing to use the system for theorem proving tasks.  
744 However, the Supervisory kernel may also contain functionality—filesystems, timers,  
745 network sockets, and similar—related to the Supervisory general-purpose virtual machine  
746 and there is a danger that this code can be used by a malefactor to *exploit* the kernel, perhaps

747 undermining the Supervisory capability system by somehow deriving a contradiction in  
748 an empty context, or similar. On balance—and focussing on security and consistency, rather  
749 than efficiency—the kernel size should be minimised if possible, as this prevents security  
750 exploits and simply moves code that must be trusted for theorem-proving purposes around,  
751 neither helping nor hindering the system’s trust story in that respect.

752 Lastly, the kernel can also be modularised—and is, in the Supervisory implementation—  
753 with all theorem-proving related material isolated inside its own module, all filesystem-related  
754 material within its own module, and the two only interacting when strictly needed. Ironically,  
755 this re-introduces the idea of protecting key system invariants using programming-language  
756 modules and type-abstraction albeit this is never directly exposed to the user.

### 757 5.3 Closing remarks

758 We have presented Supervisory, a kernel for an implementation of Gordon’s HOL. In con-  
759 trast to most implementations of HOL, Supervisory is not based on the LCF architectural  
760 pattern, but is instead implemented in a style more reminiscent of a typical operating system,  
761 making essential use of machine-oriented notions of separation to protect the system kernel  
762 from untrusted automation.

763 The Supervisory kernel—which is open-source, and developed in the open<sup>9</sup>—is imple-  
764 mented as a host for the Wasmi interpreter<sup>10</sup> for Wasm. Interpretation means that software  
765 executing under Supervisory executes orders of magnitude slower than natively-compiled  
766 code. However, the kernel is architected in a layered manner, with all important kernel  
767 functionality implemented in a library that is independent of the execution engine used  
768 and bound to the execution engine in a thin shim layer sitting between it and the core  
769 kernel library. As a result, Supervisory can be ported to more efficient Wasm execution  
770 engines—the Wasmtime just-in-time compiler<sup>11</sup>, for example—relatively easily. This porting  
771 has already started and will provide a significant increase in system performance, albeit at  
772 the cost of bringing a state-of-the-art just-in-time compiler into the kernel.

773 The design of Supervisory is interesting in its own right: it completely dispenses with  
774 the typical metalanguage associated with an LCF-style proof-assistant, allowing automation  
775 to be written in any programming language capable of respecting the Supervisory kernel  
776 binary interface and calling conventions. However, in our view the most interesting aspects of  
777 Supervisory are the consequences of its design, and the possibilities for future work. These  
778 include adopting the Supervisory kernel interface as the foundation of a hardware imple-  
779 mentation of HOL—wherein HOL’s inference rules are implemented as machine instructions  
780 that modify private memories—and the use of Supervisory as a general-purpose virtual  
781 machine that uses its proof-checking abilities to “challenge” user-space programs to explain  
782 their adherence to some system-wide security or correctness policy. Notably, by moving this  
783 proof-checking capability into the operating system, or other privileged system software, or  
784 even hardware, this capability becomes shared by *all* user-space software executing within the  
785 system, not just software written in dedicated “verification aware” programming languages.  
786 In a sense, mathematical truth becomes just another resource protected by the operating  
787 system and system hardware.

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<sup>9</sup> <https://www.github.com/DominicPM/supervisory>

<sup>10</sup> <https://github.com/paritytech/wasmi>

<sup>11</sup> <https://www.wasmtime.dev>

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